Unmanned aerial vehicle as a tool for checking the correctness of flood inundation models

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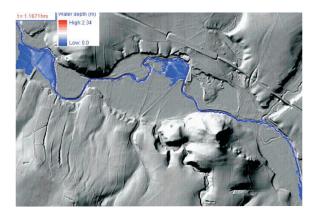
- Context
- Feasibility study
 - UAV survey
 - Experimental results

Presented material is supposed to be submitted to Journal of Hydrology within one month.

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Modelling and prediction of inundation





Visualization courtesy of Dr Dapeng Yu (Loughborough University, UK). For visualization purposes the map presents non-calibrated model.

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Pointwise and spatial hydrologic predictions

hydrologic and meteorogical data ensemble prediction from various models ((() multimodelling (for an outlet) prediction of spatial distribution of flood modelling of overbank flow VERIFICATION - testing performance in case of flood of spatial prediction warning air survey with UAV orthophoto photogrammetric air photos image processing

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UAV survey Experimental results

Research hypothesis



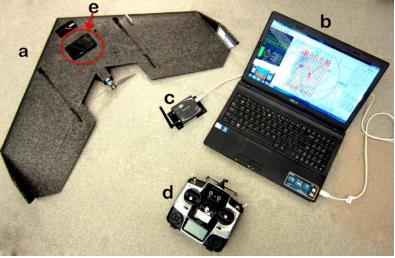
Even small inundation can be easily detected using the 3 cm/px UAV-taken photographs, and such a detection is statistically significant.

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UAV survey Experimental results

swinglet CAM





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UAV survey Experimental results

swinglet CAM - the system





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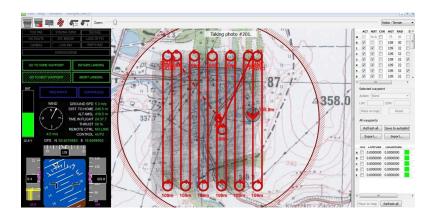
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swinglet CAM – ground base station





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UAV survey Experimental results

swinglet CAM – field work





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UAV survey Experimental results

UAV in flight – Żelazno site





UAV survey Experimental results

Individual photograph in the central projection





UAV survey Experimental results

Individual photographs in the central projection

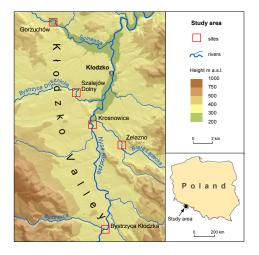




UAV survey Experimental results

Study area and five study sites





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UAV survey Experimental results

Test sites depicted on the orthophoto image, Gorzuchów

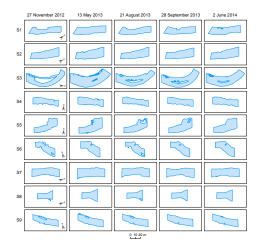




UAV survey Experimental results

UAV-observed inundation, Gorzuchów





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Data



Site ID	Inundated areas from UAV observations $[m^2]$						
	2012.11.27	2013.05.13	2013.08.21	2013.09.27	2014.06.02		
1	650.3	835.0	716.4	721.5	813.3		
2	790.1	904.6	794.7	811.1	869.0		
3	1000.1	1559.1	1168.2	1248.0	1271.3		
4	577.8	664.4	582.6	602.1	656.5		
5	651.9	804.1	628.4	747.6	803.5		
6	545.0	654.7	542.6	602.5	649.6		
7	778.6	931.7	779.6	800.3	826.9		
8	369.2	456.4	385.5	403.0	428.2		
9	584.8	708.8	658.0	678.1	692.3		

Site ID	Inundated are	eas from UAV o	bservations [%	of all inundated	areas on site
	2012.11.27	2013.05.13	2013.08.21	2013.09.27	2014.06.02
1	0.1740493	0.2234691	0.1917280	0.1930965	0.2176572
2	0.1894891	0.2169462	0.1906052	0.1945397	0.2084198
3	0.1601036	0.2495942	0.1870089	0.1997824	0.2035109
4	0.1873955	0.2154739	0.1889361	0.1952771	0.2129174
5	0.1793246	0.2211887	0.1728388	0.2056331	0.2210147
6	0.1820142	0.2186308	0.1812148	0.2012082	0.2169321
7	0.1891137	0.2262997	0.1893503	0.1943887	0.2008475
8	0.1807901	0.2234572	0.1887525	0.1973374	0.2096628
9	0.1760263	0.2133752	0.1980779	0.2041224	0.2083982

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UAV survey Experimental results

Logarithm of data



Site ID	Inundated an	eas from UAV o	bservations [log of % of all inundated areas on s		
	2012.11.27	2013.05.13	2013.08.21	2013.09.27	2014.06.02
1	-1.748417	-1.498482	-1.651678	-1.644565	-1.524834
2	-1.663424	-1.528106	-1.657551	-1.637119	-1.568201
3	-1.831934	-1.387919	-1.676599	-1.610527	-1.592036
4	-1.674534	-1.534916	-1.666346	-1.633336	-1.546851
5	-1.718558	-1.508739	-1.755396	-1.581662	-1.509526
6	-1.703671	-1.520371	-1.708072	-1.603415	-1.528171
7	-1.665407	-1.485895	-1.664156	-1.637895	-1.605209
8	-1.710419	-1.498535	-1.667318	-1.622841	-1.562255
9	-1.737122	-1.544703	-1.619095	-1.589035	-1.568305

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Statistical analysis



Test	P-value for a given observation campaign					
	2012.11.27	2013.05.13	2013.08.21	2013.09.27	2014.06.02	
Independence (Ljung-Box)	0.059	0.158	0.446	0.925	0.841	
Normality (Shapiro-Wilk)	0.171	0.013	0.219	0.370	0.843	
Symmetry (D'Agostino)	0.232	0.068	0.299	0.643	0.950	
Mesokurticity (Anscombe-Glynn)	0.142	0.012	0.144	0.319	0.542	

Date	P-value of Fisher's test between two observation campaigns					
	2012.11.27	2013.05.13	2013.08.21	2013.09.27	2014.06.02	
2012.11.27	1.000	0.732	0.390	0.029	0.173	
2013.05.13	0.732	1.000	0.601	0.060	0.301	
2013.08.21	0.390	0.601	1.000	0.162	0.603	
2013.09.27	0.029	0.060	0.162	1.000	0.369	
2014.06.02	0.173	0.301	0.603	0.369	1.000	

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UAV survey Experimental results



Date	P-value of student's test between two observation campaigns						
	2012.11.27	2013.05.13	2013.08.21	2013.09.27	2014.06.02		
2012.11.27	1.00000	0.00000	0.06493	0.00009	0.00000		
2013.05.13	0.00000	1.00000	0.00000	0.00000	0.00941		
2013.08.21	0.06493	0.00000	1.00000	0.00165	0.00000		
2013.09.27	0.00009	0.00000	0.00165	1.00000	0.00022		
2014.06.02	0.00000	0.00941	0.00000	0.00022	1.00000		

Student's test with two-sided alternative

Date	P-value of Bootstrapped student's test between two observation campaigns					
	2012.11.27	2013.05.13	2013.08.21	2013.09.27	2014.06.02	
2012.11.27	1.00000	0.00000	0.04862	0.00002	0.00000	
2013.05.13	0.00000	1.00000	0.00000	0.00000	0.00527	
2013.08.21	0.04854	0.00000	1.00000	0.00057	0.00000	
2013.09.27	0.00002	0.00000	0.00058	1.00000	0.00008	
2014.06.02	0.00000	0.00529	0.00000	0.00009	1.00000	

Student's test with two-sided alternative, B = 100000

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UAV survey Experimental results

Some flood-prone sites in orthophoto image





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UAV survey Experimental results

Conclusions



- When UAV observation during low flow is assumed to be a reference data (27/11/2012 or 21/08/2013)
 - all situations (13/05/2013, 27/09/2013, 02/06/2014) except another low flow (21/08/2013) are found to reveal significant differences in mean inundation from mean extent of water observed on 27/11/2012
 - all situations (13/05/2013, 27/09/2013, 02/06/2014) except another low flow (27/11/2012) are found to reveal significant differences in mean inundation from mean extent of water observed on 21/08/2013
- When UAV observation during moderate or peak flow is assumed to be a reference data (13/05/2013, 27/09/2013, 02/06/2014)
 - all remaining situations are found to reveal significant differences in mean inundation from mean extent of water observed on 27/11/2012 or 27/09/2013 or 02/06/2014

Acknowledgements



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Thank you for your attention

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